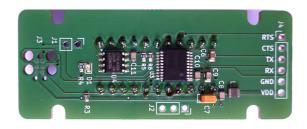
D	-0 I CMD TCD1204 EDII	-0 I CMD TCD1204 EDII
Parameter:	e9u-LSMD-TCD1304-EDU	e9u-LSMD-TCD1304-EDU
Interface:	USB 2.0	USB 2.0
Digitization depth Width of values	8 bit mode 8 bit	12 bit mode 16 bit left aligned
		S
Read noise (typ. rms)	300 e- (t.b.c.)	50 e- (t.b.c.)
Lineare Full Well Capacity	40 ke- (t.b.c.) 65 ke- (t.b.c.)	40 ke- (t.b.c.) 65 ke-(t.b.c.)
Full Scale Capacity	· · ·	
Conversion Cain (typ @ 0.4 ES)	@ 8 Bit: 330±100 e ⁻ /LSB (t.b.c.)	@ 16 Bit: 1.3±0.4 e-/LSB (t.b.c.)
Conversion Gain (typ @ 0.4 FS) Maximum line rate		
Free Run Mode with Fixed Line Rate	25 fps ×	25 fps ×
	2 0 μs	2 0 μs
Minimum exposure time	20 μs 1.3 s	20 µs 1.3 s
Maximum exposure time		
Step size exposure time	20 μs	20 μs
Read While Integrate Trigger via USB	× ✓	× ✓
66	×	×
Integration Start/Stop via USB Trigger or Start/Stop via USB latency typ.	10 ms	10 ms
Minimum / maximum baud rate	X	X X
	×	×
Trigger via UART		
Trigger via UART Latenz	× ×	X X
Trigger via UART Jitter	,	,
External Trigger Input		
External Trigger Latency	20 μs +10 μs	20 μs +10 μs
External Trigger Latency, debounced	±10 μs ×	±10 μs ×
External Trigger Latency, debounced	×	×
Isolatex external trigger input	×	×
External controll of exposure time Lantecy of exposure time controll	×	×
· ·	×	×
Minimum external exposure time Maximum external exposure time	×	×
Lantecy of exposure time controll,	^	^
debounced	×	×
Minimum external exposure time,	^	^
debounced	×	×
Trigger Output	Ĵ	Ĵ
High Resolution Timestamp: Trigger	×	×
GPIO	×	×
Frane Buffer	Ź	×
Optimized Frame Buffer	×	×
Size	^ 61 x 25 x 12 mm	61 x 25 x 12 mm
Operation Voltage	5 V (USB)	5 V (USB)
Operation Current	< 250 mA	< 250 mA
Operation Current	~ 250 IIIA	~ 250 IIIA



Dayamatayı	on, I CMD TCD1204 HADT	on, I SMD TCD1204 HADT	
Parameter: Interface:		' e9u-LSMD-TCD1304-UART UART	
	UART 9 bit mode		
Digitization depth	8 bit mode	12 bit mode	
Width of values	8 bit	16 bit left aligned	
Read noise (typ. rms)	300 e- (t.b.c.)	50 e- (t.b.c.)	
Lineare Full Well Capacity	40 ke- (t.b.c.)	40 ke- (t.b.c.)	
Full Scale Capacity	65 ke- (t.b.c.)	65 ke-(t.b.c.)	
Conversion Coin (term (2.0.4 ES)	@ 8 Bit: 330±100 e-/LSB	@ 16 Bit: 1.3±0.4 e ⁻ /LSB	
Conversion Gain (typ @ 0.4 FS)	(t.b.c.)	(t.b.c.)	
Maximum line rate	(Baudrate / 40000), max. 25 25 fps		
Free Run Mode with Fixed Line Rate	X	X	
Minimum exposure time	20 μs	20 μs	
Maximum exposure time	1.3 s	1.3 s	
Step size exposure time	20 μs	20 μs	
Read While Integrate	×	×	
Trigger via USB	×	×	
Integration Start/Stop via USB	X	×	
Trigger or Start/Stop via USB latency	X	X	
Minimum / maximum baud rate	1200 Baud bis 2 Mbaud ✓	2 Mbaud only	
Trigger via UART	•	√	
Trigger via UART Latenz	20 μs + (10 / Baudrate)	25 μs	
Trigger via UART Jitter	±10 µs + (5 / Baudrate) ✓	±13 μs ✓	
External Trigger Input	ν 20 μs	ν 20 μs	
External Trigger Litter	•	-	
External Trigger Latency, debounced	±10 μs ×	±10 μs ×	
External Trigger Latency, debounced Isolatex external trigger input	×	^ ×	
External controll of exposure time	×	×	
Lantecy of exposure time controll	×	×	
Minimum external exposure time	×	×	
Maximum external exposure time	×	×	
Lantecy of exposure time controll,	^	^	
debounced	×	×	
Minimum external exposure time,			
debounced	×	×	
Trigger Output	Ź	Ĵ	
High Resolution Timestamp: Trigger	×	×	
GPIO	×	×	
Frane Buffer	···	×	
Optimized Frame Buffer	×	×	
Size	61 x 25 x 12 mm	61 x 25 x 12 mm	
Operation Voltage	3.3 V	3.3 V	
Operation Current	< 250 mA	< 250 mA	
Sporation Carrott	- 200 111/1	- 200 110 (



UART Configuration:

USB-Version: Bits:

Parity: none Stop Bits:

Baud Rate: 3 Mbaud

UART-Version: Bits:

Parity: none Stop Bits: 1

Baud Rate: min. 1200 Baud to max. 2 Mbaud

Startup:

up on power up, wait for 100 ms and discard any traffic on the UART, then send:

"U" like UART 0x55

to generate an alternating pattern on TX:

...1 0 10101010 1 1...

this is used to detect the frequency and set the baud rate

Response:

none

0x49 "I" like Identify

Response:

if the Baud rate was successfully detected, the camera answers with 21 Bytes: 0x65 39 75 5f 4c 53 4d 44 2d 54 43 44 31 33 30 34 2d 45 44 55 00 "e9u_LSDM-TCD1304-EDU"

If this does not work, transmit a BREAK and try again:

BREAK keep TX line low for long time, this resets the camera then wait for 100 ms and discard any traffic on the UART

0x55 "U" like UART

Response:

none

"I" like Identify 0x49

Response:

21 Bytes: 0x65 39 75 5f 4c 53 4d 44 2d 54 43 44 31 33 30 34 2d 45 44 55 00 "e9u_LSDM-TCD1304-EDU"

10/24/25

Camera Configuration:

```
0x31 "1" like one byte per pixel (default)
      enables the 8-bit mode:
      8 bit ADC, 8-bit values
      Response:
      none
0x32 "2" like two bytes per pixel
      enables the 16-bit mode:
      12-bis ADC, 16-bit values left justified little endian
      Response:
      none
0x41 "A" like "Alive",
      send keep alive 0xff bytes every 98.3 ms
      Response:
      none
     "a" like not "alive" (default)
      do not send keep alive bytes
      Response:
      none
     "T" like "Trigger"
0x54
      enable hardware trigger input at J2
      Response:
      none
0x74 "t" like no "trigger" (default)
      disable hardware trigger input
      Response:
      none
     "P" like write "Protection" (default)
0x50
      protects offset from being changed
      Response:
      none
     "p" like no write "protection",
0×70
      needs to be sent just after startup and requires hardware jumper at J1
      allows offset to be changed
      Response:
      none
```

Operation:

```
0x53
     "S" like "Scan"
      starts exposure of one scan,
      if the exposure is longer than 100 ms,
      keep alive packages are sent if enabled
      Response:
      After exposure the pixel values are transmitted:
                        0x0000 for synchronization
      SYNC 16 bit
           16 bit
                        two bytes containing the exposure time little endian
      EXP
      FLAGS 8 bit
                        one byte containing the configuration flags (see below)
      PIXEL 3648 words
            1 byte mode: one byte per word
            2 byte mode: two byte per word, little endian, left aligned
     "E" like "Exposure" time
0x45
      direct followed by a 16 bit little endian value
      representing the exposure time in 20 µs steps
      Response:
      none
      "O" like "Offset" correction, if write protect is disabled
      directly followed by an 8 bit value
      representing the analog offset voltage
      Response:
      none
```

Special functions:

```
0x52 "R" like "Read" from EEPROM
      Response:
      16384 bytes
0x57 "W" like "Write" to EEPROM, if write protect is disabled
      directly followed by 2 byte for address, big endian
      directly followed by 64 bytes of data
      make sure that the address is multiple of 64
      Response:
      none
Oxff !Sync stay alive
      Response:
      none
0x55
     "U" UART
      go back to initialization, used to restart the camera
      Response:
      none
```

Flags:

Bit 0 (0x01)	TWOBYTE	= 16 Bit Mode
Bit 1 (0x02)	TRIGEREN	= external trigger is enabled
Bit 2 (0x04)	reserved	
Bit 3 (0x08)	reserved	
Bit 4 (0x10)	reserved	
Bit 5 (0x20)	WPDIS	<pre>= write protect is DISABLED</pre>
Bit 6 (0x40)	ALIVEEN	= keep alive packages are enabled
Bit 7 (0x80)	HIGHSPEED	= 3 Mbaud enabled

Notes:

- A. The interface protocol is kept very simple to reduce overhead and allow an easy control via small micro controllers and/or scripts.

 The result is a compromise between complexity, flexibility and features.
- B. The camera has three operation sequences:
 - 1. Idle: the camera waits for commands or trigger
 - 2. Exposure: the camera was triggered and exposure is in progress NOTE: during this time, no commands can be sent!
 - 3. Readout: the sensor is read out and the pixel values are transferred NOTE: during this time, no commands can be sent!
- C. To avoid time outs and/or race conditions at the host, the camera can be configured to send single 0xff byte as keep alive packages every 98.3 ms after the last traffic on the interface. A 0xff byte received outside of the pixel values can be discarded.
- D. The camera resets, if communication is lost and the transmit buffer overflows.

If Keep-Alive packages are activated, the camera resets, if the packages are not received by the host just in time. Depending on the interface the buffer size varies:

- USB: up to 512 packages the camera resets, if the buffer is not read for 50.5 ms, to avoid a camera reset regularly read within 20 s!
- 2. UART: only 2 packages the camera resets, if the buffer is not read for 196 ms, to avoid a camera reset regularly read within 100 ms!
- E. The pixel values are transmitted during read out:
 - 1. 8-Bit mode: the pixel values are buffered in a FIFO and could be read out slowly
 - 2. 12-Bit mode: the pixel values are not buffered and must be read at full speed with 200 Byte per second!